## OmROn

## A Large Revolution in a Small Body <br> CompoBus/S Series

SRIM1 s-Controller


# CompoBus/S Master and Machin Functionality All in a Body This S 

The SRM1 is the Master Unit for OMRON's CompoBus/S Series.
It controls up to 256 I/O points while also performing machine control as a programmable controller.
A revolutionary small body reduces space requirements in control panels while distributing I/O and reducing wiring.

## SRINE <br> Version 2

- The SRM1 can now handle analog signals, with 4-point Input Units and 2-point Output Units added to the series.
- Long-distance communications are now supported; wiring can be reduced for communications at distances of up to 500 m when using CTF cable.
- PT connection via 1:N NT Link is now possible.


## e Controller mall



The SRM1 controls machines as a programmable controller. Despite its size the SRM1 boasts a wealth of functionality supported by a 4-Kword program capacity, a 2-Kword data memory capacity, 14 basic instructions, and 81 special instructions. In addition, the SRM1 can control up to 256 I/O points as a CompoBus/S Master Unit. Use CompoBus/S Slaves to control up to 128 input and 128 output points.


The SRM1 scan time for 500 steps with basic instructions is 1.37 ms , including the CompoBus/S communications time (see note). This kind of high-speed processing makes it hard to believe that the system is handling remote I/O!

Note: The figure of 1.37 ms is with 16 Slaves. With 32 Slaves, it is 1.67 ms .

Processing for CompoBus/S
communications is performed after outputs are refreshed and then after communications is completed, inputs are refreshed. This means that CompoBus/S communications is performed once without fail within one
 scan.

# A Compact Body and Easy Instal a Wide Range of Applications 

## Product Lineup

RS-232C Communications Devices


Connector Terminal (with sensor connectors; 8 points)


Transistor Remote Terminal (with three-row terminal block; 16 points)

SRM1


Programming Device


High-speed remote CompoBus/S system with 4-Kwords of user memory and 2-Kwords of data memory.
-Up to 128 inputs and 128 outputs (with 32 Slaves). © Main line length 100 m max.; Total branch line length: 50 m max. (high-speed communications mode) - Main line length: 500 m max.; Total branch line length: 120 m max. (long-distance communications mode)


T-branch Connection Supported

## -Special flat cable

## I/O Link Unit

(8 inputs and
8 outputs)
 T-shape pressure-welded connectors.


Expansion with relay terminal block.

Relay-mounted Remote Terminal (8 or 16 points)

## lation for

## Miniafure Devices Applications

Pressing Equipment

- Create a vertical control panel using the SRM1.
- Delivery the machine and the control panel together as one block instead of separately.



## Device Expansion

- The system can be easily expanded with a wide range of Slave Units. - Slave Units can be arranged according to requirements.



## Monitoring Applications

## Monitoring Boiler Status



Boiler \#1

- Construct a special board and mount it in the boiler. - Control all the boilers simultaneously from the monitor room using the SRM1.


Boiler \#n

Operator Interface for Mixed Foodstuff Work Instructions

- Using bar codes and display devices for work instructions eliminates careless mistakes.
- Data checks can be performed after work is finished, enabling efficient product management.



## Non-FA Applications

## Locking Control for Emergency Exits

- By installing a Sensor Terminal on every floor, all the exits can be monitored from just one SRM1 on the first floor. - Status monitoring and locking can be performed using display devices.



## Multi-level Parking Lots

- Space availability can be confirmed from one control room. - Up to 256 points can be connected with one SRM1 enabling management of large-scale parking facilities.


Switch, lamp, buzzer

# Connect to PTs, Computers, or P Easy Operation and Data Manage 

## Connection to PTs



## LCs for

## ment

## Connection to Computers

-1:1 Host Link Communications

versions 2.0 or late
-1:n Host Link Communications


## Connections Between 2 SRM1s and a Host PLC

-Connections Between 2 SRM1s and a Host PLC


# CompoBus/S Slave Units 

## CPM2C-SRT21

I/O Link Unit
I/O Link Unit for SYSMAC CPM2C PLCs

- Functions as the Slave of a CompoBus/S Master Unit.
- Number of points for I/O with the Master Unit: 8



## CPM1A-SRT21 <br> I/O Link Unit

I/O Link Unit for CPM2A/CPM1A PLCs

- Functions as the Slave of a CompoBus/S Master Unit.
inputs and 8 outputs.
- Number of points for I/O with the Master

Unit: 8 inputs and 8 outputs.

- Applicable standards: UL, CSA, CE.



## SRT2-ID/OD(-1)

Transistor Remote Terminals
Miniature remote terminals with 4, 8, or 16 transistor I/O points

- Both 4-points models and 8-points models have ultra-miniature dimensions: $80 \times 50 \times 45 \mathrm{~mm}(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$.
- Internal circuits and I/O circuits are isolated and so separate power supplies can be used.
- Both DIN track mounting and screw mounting models are available.




## SRT2-R

Relay-mounted Remote Terminals
Relay-mounted ultra-miniature Remote Terminals with 8 or 16 outputs

- Ultra-miniature dimensions: $101 \times 51 \times 51 \mathrm{~mm}(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$ for 8-point models and $156 \times 51 \times 51 \mathrm{~mm}(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$ for 16 -point models.
- Internal circuits and I/O circuits are isolated and so separate power supplies can be used.
- Relay models and power MOS FET relay models are included in the lineup.
- Both DIN track mounting and screw mounting models are available.
 8 relay outputs

SRT2-ROF08 8 power MOS 8 power M
FET relay FET relay
outputs


## SRT2-ROC16

 16 relay outputs
## SRT2-ROF16 16 power MOS <br> 16 power M FET relay FET relay outputs



SRT2- $\square$ D16T(-1)
Transistor Remote Terminals with 3-Tier Terminal Blocks
Transistor Remote Terminals with 3-tier terminal blocks (16 points) have been added to the series. Up to 6 different models are available including input-only models, output-only models, mixed-I/O models, and both NPN and PNP models.
-Wiring is simple. (No common tightening; wiring positions easily identified.)

- Easier system design and reduced wiring.
- Cassette-mounting construction used for the circuit.



## SRT2-VID/VOD(-1)

Connector Terminals (8 Points or 16 Points)
Remote I/O terminals that enable wiring reductions, downsizing, and long-distance communications

- Switching possible between long-distance and high-speed modes.
- Connectors used for I/O, enabling system downsizing.
- Use of connectors also makes wiring easier.
- DIN track attachment allows greater flexibility with mounting.
- Sensor connector models and MIL connector models available with the same dimensions.

SRT2-V $\square$ D08S(-1) Sensor Connector


SRT2-V $\square$ D16ML(-1) MIL Connector


## SRT2- $\square$ 32ML(-1)

Connector Terminals (32 Points)
Compact 32-point remote terminals

- Compact dimensions: $35 \times 60 \times 80 \mathrm{~mm}$ (WxDxH)
- Up to 6 different models are available including input-only models, output-only models, mixed-l/O models, and both NPN and PNP models.
- Switching possible between longdistance and high-speed modes.



## SRT2-AD04

Analog Input Terminal
Compact Analog Input Terminal with the same dimensions as a 16-point Remote Terminal

- The number of input points can be set according requirements: 4 max
- Resolution: $1 / 6000$.
- High-speed conversion: 1 ms per point.
- Wide input range available.
- Dimensions: $105 \times 50 \times 48 \mathrm{~mm}(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$



## SRT2-DA02

## Analog Output Terminal

Compact Analog Output Terminal with the same
dimensions as a 16 -point Remote Terminal

- The number of output points can be set to either 1 or 2.
- Resolution: $1 / 6000$
- Dimensions: $105 \times 50 \times 48 \mathrm{~mm}$
(W x D x H)



## SRT1- $\square \square$ D04S

Sensor Amplifier Terminals
One-touch connection of sensor amplifiers enables significant wiring reductions.

- Costs reduced and space saved by connecting to a 4-channel Connector Unit for photoelectric sensors.
- A Terminal Block Unit, handy for connecting to sensors with built-in amplifiers and limit switches, is also included in the lineup.
- By using expansion blocks, up to 8 channels of sensor input can be made available.
- Connection to proximity sensors is also supported.


Connector Units (for Photoelectric Sensors)


Connector Units (for Proximity Sensors)
Terminal Block Unit E2CY-T16
Aluminum detection

E39-JID01
1 input

## SRT1-ID $\square$ P/OD $\square \mathbf{P}$

Remote I/O Modules
Modular models that can be mounted on PCBs

- Compact dimensions: $60 \times 35 \times 16 \mathrm{~mm}(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$.
- 16 -point input and 16 -point output models available.



## SRT1- $\square$ D08S

Sensor Terminals
Easy connection to sensors using connectors.

- Easy mounting of sensors with XS8 connectors.
- 2-wire sensors can also be connected.
- With the mixed-I/O model, remote teaching is possible with the PLC using output signals.


SRT1-ID08S 8 inputs


## CompoBus/S Slave Units

FND-X $\square \square \square$-SRT
CompoBus/S Position Driver
Easy-to-use servo drivers with positioning functionality

- Can be connected to $30-\mathrm{W}$ to $2.2-\mathrm{kW}$ servomotors.
- Feature 2 modes: feeder control and PTP control.
- Positioning is performed simply by specifying a point number and turning on the start signal.


Recommended Power Supplies
These products provide the DC power supply required for all types of I/O devices.
CPM2C-PA201


| Model | Input <br> voltage | Output <br> voltage | Output <br> current | Output <br> capacity | External dimensions (mm) <br> $\mathrm{H} \times \mathrm{W} \times \mathrm{D}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CPM2C-PA201 | 100 to 240 <br> VAC | 24 V | 0.6 A | 15 W | $90 \times 40 \times 60$ <br> (not including the terminals) |

For details, refer to SYSMAC CPM2A/CPM2C (P049).


| Model | Input voltage | Output power supply/current | Output capacity | External dimensions (mm) $\mathrm{H} \times \mathrm{W} \times \mathrm{D}$ |
| :---: | :---: | :---: | :---: | :---: |
| S82K-00324 | 100 to 240 VAC | $24 \mathrm{VDC}, 0.13 \mathrm{~A}$ | 3W | $75 \times 37.5 \times 65$ |
| S82K-00724 |  | $24 \mathrm{VDC}, 0.3 \mathrm{~A}$ | 7.5W |  |
| S82K-01524 | 100 to 240 VAC | $24 \mathrm{VDC}, 0.6 \mathrm{~A}$ | 15W | $75 \times 45 \times 96$ |
| S82K-03024 |  | $24 \mathrm{VDC}, 1.3 \mathrm{~A}$ | 30W | $75 \times 90 \times 96$ |
| S82K-05024 |  | $24 \mathrm{VDC}, 2.1 \mathrm{~A}$ | 50W |  |
| S82K-10024 | 100/200 VAC switchable | $24 \mathrm{VDC}, 4.1 \mathrm{~A}$ | 100W | $75 \times 145 \times 96$ |

For details, refer to Power Supply Selection Guide (Y102).

Note: Do not use this document to operate the Unit.

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## Authorized Distributor:

## Specifications

## General Specifications

| Item | SRM1-C01/02-V2 |
| :--- | :--- |
| Supply voltage | 24 VDC |
| Allowable supply voltage | 20.4 to 26.4 VDC |
| Power consumption | 3.5 W max. |
| Inrush current | 12.0 A max. |
| Noise immunity | 2 kV , conforming to IEC61000-4-4 (power lines) |
| Vibration resistance | 10 to $57 \mathrm{~Hz}, 0.075-\mathrm{mm}$ amplitude, 57 to 150 Hz, acceleration: $9.8 \mathrm{~m} / \mathrm{s}^{2}$ in $\mathrm{X}, \mathrm{Y}$, and Z <br> directions for 80 minutes each <br> (Time coefficient; 8 minutes $\times$ coefficient factor 10 = total time 80 minutes) |
| Shock resistance | $147 \mathrm{~m} / \mathrm{s}^{2}$ three times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-20^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| Humidity | $10 \%$ to $90 \%$ (with no condensation) |
| Atmosphere | Must be free from corrosive gas. |
| Terminal screw size | M 3 |
| Power interrupt time | DC type: 2 ms min. |
| Weight | $150 \mathrm{~g} \mathrm{max}$. |

## Performance Specifications

| Item | SRM1-C01/02-V2 |
| :---: | :---: |
| Control method | Stored program method |
| I/O control method | Cyclic scan method |
| Programming language | Ladder diagram |
| Instruction length | 1 step per instruction, 1 to 5 words per instruction |
| Types of instructions | Basic instructions: 14 <br> Special instructions: 81 instructions, 125 variations |
| Execution time | Basic instructions: $0.97 \mu \mathrm{~s}$ (LD instruction) <br> Special instructions: $9.1 \mu \mathrm{~s}$ (MOV instruction) |
| Program capacity | 4,096 words |
| Maximum number of I/O points | 256 points (IN 128 points/OUT 128 points) |
| Input bits | 160 bits: 00000 to 00715 (Bits not used as input bits can be used as work bits.) |
| Output bits | 160 bits: 01000 to 01715 (Bits not used as output bits can be used as work bits.) |
| Work bits | 704 bits: 00800 to 00915 (Words IR 008 and IR 009) 01800 to 01915 (Words IR 018 and IR 019) 20000 to 23915 (Words IR 200 to IR239) |
| Special bits (SR area) | 248 bits: 24000 to 25507 (Words IR 240 to IR 255) |
| Temporary bits (TR area) | 8 bits (TR0 to TR7) |
| Holding bits (HR area) | 320 bits: HR 0000 to HR 1915 (Words HR 00 to HR 19) |
| Auxiliary bits (AR area) | 256 bits: AR 0000 to AR 1515 (Words AR 00 to AR 15) |
| Link bits (LR area) | 256 bits: LR 0000 to LR 1515 (Words LR 00 to LR 15) |
| Timers/Counters | 128 timers/counters (TIM/CNT 000 to TIM/CNT 127) <br> 100-ms timers: TIM 000 to TIM 127 <br> 10-ms timers (high-speed counter): TIM 000 to TIM 003 <br> Decrementing counters and reversible counters <br> (Note: A malfunction may occur if the cycle time is over 10 ms when TIM 004 to TIM 127 are used with the TIMH instruction.) |
| Data memory | Read/Write: 2,022 words (DM 0000 to DM 2021) Read-only: 512 words (DM 6144 to DM 6655) |
| Interval timer interrupts | One-shot mode / Scheduled interrupt mode, one bit (0.5 to 319.968 ms ) |

## Specifications

| Item | SRM1-C01/02-V2 |
| :--- | :--- |
| Memory protection | HR, AR, and DM area contents; and counter values maintained during power <br> interruptions. |
| Memory backup | Flash memory: <br> The program and read-only DM area are backed up without a battery. <br> Capacitor backup: <br> The read/write DM area, HR area, AR area, and counter values are backed up by a <br> capacitor for 20 days at $25^{\circ} \mathrm{C}$. The capacitor backup time depends on the ambient <br> temperature. See the graph on the following page for details. |
| Self-diagnostic functions | CPU failure (watchdog timer), memory check, communications errors, setting errors |
| Program checks | No END instruction, programming errors (continuously checked during operation) |
| Peripheral port | One point; tool connection, Host Link, no protocol |
| RS-232C Port | One point (SRM1-C02-V2 only); Host Link, 1:1 NT Link, 1:N NT Link, 1:1 PC Link, no <br> protocol |

## - CompoBus/S Communications Specifications

| Item |  |  |
| :--- | :--- | :--- |
| Communications method | CompoBus special protocol |  |
| Transmission method <br> (See note 1.) | High-speed <br> communications <br> mode | Long-distance <br> communications <br> mode |

Note: 1. Changed using a DIP switch. (Switched using DM Area settings. Default setting $=750 \mathrm{kbit} / \mathrm{s}$.)

## Specifications

2. When the total number of connected Slaves is 16 or less, communications are possible with a main line length of 100 m max. and a total branch line length of 50 m max .
3. There are no restrictions on the branching configuration, main line length, branch line length, and total branch line length. Connect a terminating resistance to the point in the system farthest away from the Master.

- Memory Area Allocations

| Name |  | Number of bits | Word addresses | Bit addresses | Function |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input area |  | 160 (10 words) | IR 000 to IR 009 | $\begin{aligned} & \hline \text { IR } 00000 \text { to IR } \\ & 00915 \end{aligned}$ | These bits can be allocated to CompoBus/S. (Words that are not used for input or output can be used as work words.) |
| Output area |  | 160 (10 words) | IR 010 to IR 019 | $\begin{aligned} & \text { IR } 01000 \text { to IR } \\ & 01915 \end{aligned}$ |  |
| Work area |  | 640 (40 words) | IR 200 to IR 239 | $\begin{aligned} & \text { IR } 20000 \text { to IR } \\ & 23915 \end{aligned}$ | These bits can be used freely within the program. |
| SR area |  | 248 | IR 240 to IR 255 | $\begin{aligned} & \text { IR } 24000 \text { to IR } \\ & 25507 \end{aligned}$ | These bits are used for specific functions. |
| TR area |  | 8 | TR 0 to TR 7 |  | These bits are used to temporarily store the status of branch points in instruction blocks. |
| HR area |  | 320 (20 words) | HR 00 to HR 19 | $\begin{array}{\|l} \hline \text { HR } 0000 \text { to } \mathrm{HR} \\ 1915 \end{array}$ | These bits can be freely used within the program. Their statuses are held when power is interrupted. |
| AR area |  | 256 (16 words) | AR 00 to AR 15 | $\begin{array}{\|l\|} \hline \text { AR } 0000 \text { to AR } \\ 1515 \end{array}$ | These bits are used for specific functions. AR 04 to AR 07 are used as Slave Status Flags. |
| LR area |  | 256 (16 words) | LR 00 to LR 15 | $\begin{aligned} & \text { LR } 0000 \text { to LR } \\ & 1515 \end{aligned}$ | These bits are used for 1 -to- 1 links for data I/O. (They can also be used as work bits.) |
| TIM/CNT area |  | 128 | TIM/CNT 000 to TIM/CNT 127 |  | These bits are used for timers and counters. The same bit can be used for either a timer or a counter. |
| DM area | Read/Write only | 2022 words | DM 0000 to DM 2021 |  | These bits are used in word units (i.e. in 16 -bit blocks). Their statuses are held when power is interrupted. DM 6144 to DM 6599 and DM 6600 to DM 6655 cannot be written to from the program. (They can, however, be set from a Programming Device.) |
|  | Read only | 456 words | DM 6144 to DM 6599 |  |  |
|  | PC Setup | 56 words | DM 6600 to DM 6655 |  |  |

# Programming Instructions 

## Summary of Programming Instructions

## ■ Function Code Chart

| Table <br> sym- <br> bols | Details | Key operations for <br> specifying program- <br> ming instructions |
| :--- | :--- | :--- |
| - | Allocated to instruction <br> keys on the Program- <br> ming Console. These <br> need not be specified <br> with function codes. | --- |
| Code | Special instructions <br> specified with function <br> codes. | FUN $\rightarrow$ Code $\rightarrow$ WRITE |
| $\star$ | Expansion instructions. <br> The following opera- <br> tions are required in or- <br> der to use these <br> instructions. | (After sorting <br> operations) |

## ■ Differentiated Instructions

Differentiated instructions can sometimes be used for SRM1 special instructions. Instructions marked with (@) in the mnemonics can also be used as differentiated instructions. Here the input rise time (shift from OFF to ON) is used to execute the instruction in just one cycle.
To specify an instruction, press the NOT Key after the function code.
Example: Specifying the @MOV (21) instruction


## - Sequence Instructions

## Sequence Input Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| LOAD | LD | $\bigcirc$ | Connects an NO condition to <br> the left bus bar. |
| LOAD NOT | LD NOT | $\bigcirc$ | Connects an NC condition to <br> the left bus bar. |
| AND | AND | $\bigcirc$ | Connects an NO condition in <br> series with the previous condi- <br> tion. |
| AND NOT | AND NOT | $\bigcirc$ | Connects an NC condition in <br> series with the previous condi- <br> tion. |
| OR | OR | $\bigcirc$ | Connects an NO condition in <br> parallel with the previous <br> condition. |
| OR NOT | OR NOT | $\bigcirc$ | Connects an NC condition in <br> parallel with the previous <br> condition. |
| AND LOAD | AND LD | $\bigcirc$ | Connects two instruction <br> blocks in series. |
| OR LOAD | OR LD | $\bigcirc$ | Connects two instruction <br> blocks in parallel. |

Note: $\bigcirc$ : Instruction keys allocated to the Programming Console.

## Sequence Output Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| OUTPUT | OUT | $\bigcirc$ | Outputs the result of logic to a <br> bit. |
| OUT NOT | OUT NOT | $\bigcirc$ | Reverses and outputs the re- <br> sult of logic to a bit. |
| SET | SET | $\bigcirc$ | Force sets (ON) a bit. |
| RESET | RSET | $\bigcirc$ | Force resets (OFF) a bit. |
| KEEP | KEEP | 11 | Maintains the status of the <br> designated bit. |
| DIFFER- <br> ENTIATE <br> UP | DIFU | 13 | Turns ON a bit for one cycle <br> when the execution condition <br> goes from OFF to ON. |
| DIFFER- <br> ENTIATE <br> DOWN | DIFD | 14 | Turns ON a bit for one cycle <br> when the execution condition <br> goes from ON to OFF. |

Note: $\bigcirc$ : Instruction keys allocated to the Programming Console.

## Sequence Control Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| NO <br> OPERA- <br> TION | NOP | 00 | --- |
| END | END | 01 | Required at the end of the pro- <br> gram. |
| INTER- <br> LOCK | IL | 02 | If the execution condition for <br> IL(02) is OFF, all outputs are <br> turned OFF and all timer PVs <br> reset between IL(02) and the <br> next ILC(03). |
| INTER- <br> LOCK <br> CLEAR | ILC | 03 | ILC(03) indicates the end of an <br> interlock (beginning at IL(02)). |
| JUMP | JMP | 04 | If the execution condition for <br> JMP(04) is ON, all instructions <br> between JMP(04) and <br> JME(05) are treated as <br> NOP(00). |
| JUMP END | JME | 05 | JME(05) indicates the end of a <br> jump (beginning at JMP(04)). |

- Timer/Counter Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| TIMER | TIM | $\bigcirc$ | An ON-delay (decrementing) <br> timer. |
| COUNTER | CNT | $\bigcirc$ | A decrementing counter. |
| RE- <br> VERSIBLE <br> COUNTER | CNTR | 12 | Increases or decreases PV by <br> one. |
| HIGH- <br> SPEED <br> TIMER | TIMH | 15 | A high-speed, ON-delay <br> (decrementing) timer. |

Note: $\bigcirc$ : Instruction keys allocated to the Programming Console.

## Programming Instructions

Step Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| STEP DE- | STEP | 08 | Defines the start of a new step <br> and resets the previous step <br> when used with a control bit. <br> DiNE |
| Defines the end of step execu- |  |  |  |
| tion when used without a con- |  |  |  |
| trol bit. |  |  |  |

Increment/Decrement Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| INCRE- <br> MENT | (@)INC | 38 | Increments the BCD content of <br> the specified word by 1. |
| DECRE- <br> MENT | (@)DEC | 39 | Decrements the BCD content <br> of the specified word by 1. |

BCD/Binary Calculation Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| BCD ADD | (@)ADD | 30 | Adds the content of a word (or <br> a constant). |
| BCD SUB- <br> TRACT | (@)SUB | 31 | Subtracts the content of a <br> word (or constant) and CY <br> from the content of a word (or <br> constant). |
| BCD MUL- <br> TIPLY | (@)MUL | 32 | Multiplies the contents of two <br> words (or constants). |
| BCD DI- <br> VIDE | (@)DIV | 33 | Divides the content of a word <br> (or constant) by the content of <br> a word (or constant). |
| BINARY <br> ADD | (@)ADB | 50 | Adds the contents of two <br> words (or constants) and CY. |
| BINARY <br> SUB- <br> TRACT | (@)SBB | 51 | Subtracts the content of a <br> word (or constant) and CY <br> from the content of a word (or <br> constant). |
| BINARY <br> MULTIPLY | (@)MLB | 52 | Multiplies the contents of two <br> words (or constants). |
| BINARY <br> DIVIDE | (@)DVB | 53 | Divides the content of a word <br> (or constant) by the content of <br> a word and obtains the result <br> and remainder. |
| DOUBLE <br> BCD ADD | (@)ADDL | 54 | Add the 8-digit BCD contents <br> of two pairs of words (or <br> constants) and CY. |
| DOUBLE <br> BCD SUB- <br> TRACT | (@)SUBL | 55 | Subtracts the 8-digit BCD con- <br> tents of a pair of words (or <br> constants) and CY from the <br> 8-digit BCD contents of a pair <br> of words (or constants). |
| DOUBLE <br> BCD MUL- <br> TIPLY | (@)MULL | 56 | Multiplies the 8-digit BCD con- <br> tents of two pairs of words (or <br> constants). |
| DOUBLE <br> BCD DI- <br> VIDE | (@)DIVL | 57 | Divides the 8-digit BCD con- <br> tents of a pair of words (or <br> constants) by the 8-digit BCD <br> contents of a pair of words (or <br> constants). |

## ■ Data Conversion Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| BCD TO <br> BINARY | (@)BIN | 23 | Converts 4-digit BCD data to <br> 4-digit binary data. |
| BINARY <br> TO BCD | (@)BCD | 24 | Converts 4-digit binary data to <br> 4-digit BCD data. |
| 4 TO 16 <br> DECODER | (@)MLPX | 76 | Takes the hexadecimal value <br> of the specified digit(s) in a <br> word and turns ON the corre- <br> sponding bit in a word(s). |
| 16 TO 4 <br> DECODER | (@)DMPX | 77 | Identifies the highest ON bit in <br> the specified word(s) and <br> moves the hexadecimal val- <br> ue(s) corresponding to its <br> location to the specified digit(s) <br> in a word. |
| ASCII <br> CODE <br> CONVERT | (@)ASC | 86 | Converts the designated dig- <br> it(s) of a word into the equiva- <br> lent 8-bit ASCII code. |
| 2'S COM- <br> PLEMENT <br> (-V2 mod- <br> els only) | (@)NEG | $\star$ | Converts the four-digit hexade- <br>  <br> cimal content of the source <br> word to its 2's complement <br> and outputs the result to R. |

## Data Comparison Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| COMPARE | CMP | 20 | Compares two four-digit hexa- <br> decimal values. |
| DOUBLE <br> COMPARE | CMPL | 60 | Compares two eight-digit hex- <br> adecimal values. |
| BLOCK <br> COMPARE | (@)BCMP | 68 | Judges whether the value of a <br> word is within 16 ranges (de- <br> fined by lower and upper lim- <br> its). |
| TABLE <br> COMPARE | (@)TCMP | 85 | Compares the value of a word <br> to 16 consecutive words. |
| AREA <br> RANGE <br> COMPARE <br> (-V2 mod- <br> els only) | ZCP | $\star$ | Compares a word to a range <br> defined by lower and upper <br> limits and outputs the result to <br> the GR, EQ, and LE flags. |

## Programming Instructions

Data Movement Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| MOVE | (@)MOV | 21 | Copies a constant or the con- <br> tent of a word to a word. |
| MOVE <br> NOT | (@)MVN | 22 | Copies the complement of a <br> constant or the content of a <br> word to a word. |
| BLOCK <br> TRANS- <br> FER | (@)XFER | 70 | Copies the content of a block <br> of up to 1,000 consecutive <br> words to a block of consecu- <br> tive words. |
| BLOCK <br> SET | (@)BSET | 71 | Copies the content of a word <br> to a block of consecutive <br> words. |
| DATA EX- <br> CHANGE | (@)XCHG | 73 | Exchanges the content of two <br> words. |
| SINGLE <br> WORD <br> DIS- <br> TRIBUTE | (@)DIST | 80 | Copies the content of a word <br> to a word (whose address is <br> determined by adding an offset <br> to a word address). |
| DATA COL- <br> LECT | (@)COLL | 81 | Copies the content of a word <br> (whose address is determined <br> by adding an offset to a word <br> address) to a word. |
| MOVE BIT | (@)MOVB | 82 | Copies the specified bit from <br> one word to the specified bit of <br> a word. |
| MOVE <br> DIGIT | (@)MOVD | 83 | Copies the specified digits <br> (4-bit units) from a word to the <br> specified digits of a word. |

## ■ Logic Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| COMPLE- <br> MENT | (@)COM | 29 | Turns OFF all ON bits and <br> turns ON all OFF bits in the <br> specified word. |
| LOGICAL <br> AND | (@)ANDW | 34 | Logically ANDs the corre- <br> sponding bits of two words (or <br> constants). |
| LOGICAL <br> OR | (@)ORW | 35 | Logically ORs the correspond- <br> ing bits of two words (or <br> constants). |
| EXCLU- <br> SIVE OR | (@)XORW | 36 | Exclusively ORs the corre- <br> sponding bits of two words (or <br> constants). |
| EXCLU- <br> SIVE NOR | (@)XNRW | 37 | Exclusively NORs the corre- <br> sponding bits of two words (or <br> constants). |

## Shift Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| SHIFT <br> REGISTER | SFT | O/10 | Copies the specified bit (0 or <br> 1) into the rightmost bit of a <br> shift register and shifts the oth- <br> er bits one bit to the left. |
| WORD <br> SHIFT | (@)WSFT | 16 | Creates a multiple-word shift <br> register that shifts data to the <br> left in one-word units. |
| ASYNCH- <br> RONOUS <br> SHIFT <br> REGISTER | (@)ASFT | 17 | Creates a shift register that ex- <br> changes the contents of adja- <br> cent words when one is zero <br> and the other is not. |
| ARITH- <br> METIC <br> SHIFT <br> LEFT | (@)ASL | 25 | Shifts a 0 into bit 00 of the <br> specified word and shifts the <br> other bits one bit to the left. |
| ARITH- <br> METIC <br> SHIFT <br> RIGHT | (@)ASR | 26 | Shifts a 0 into bit 15 of the <br> specified word and shifts the <br> other bits one bit to the right. |
| ROTATE <br> LEFT | (@)ROL | 27 | Moves the content of CY into <br> bit 00 of the specified word, <br> shifts the other bits one bit to <br> the left, and moves bit 15 to <br> CY. |
| ROTATE <br> RIGHT | (@)ROR | 28 | Moves the content of CY into <br> bit 15 of the specified word, <br> shifts the other bits one bit to <br> the right, and moves bit 00 to <br> CY. |
| ONE DIGIT <br> SHIFT <br> LEFT | (@)SLD | 74 | Shifts a 0 into the rightmost <br> digit (4-bit unit) of the shift reg- <br> ister and shifts the other digits <br> one digit to the left. |
| ONE DIGIT <br> SHIFT <br> RIGHT | (@)SRD | 75 | Shifts a 0 into the leftmost digit <br> (4-bit unit) of the shift register <br> and shifts the other digits one <br> digit to the right. |
| RE- <br> VERSIBLE <br> SHITT <br> REGISTER | (@)SFTR | 84 | Creates a single or multiple- <br> word shift register that can <br> shift data to the left or right. |

Note: $\bigcirc$ : Instruction keys allocated to the Programming Console.

## Special Calculation Instruction

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| BIT <br> COUNTER | (@)BCNT | 67 | Counts the total number of bits <br> that are ON in the specified <br> block of words. |

## Programming Instructions

## Subroutine Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| SUBROU- <br> TINE EN- <br> TER | (@)SBS | 91 | Executes a subroutine in the <br> main program. |
| SUBROU- <br> TINE <br> ENTRY | SBN | 92 | Marks the beginning of a sub- <br> routine program. |
| SUBROU- <br> TINE RE- <br> TURN | RET | 93 | Marks the end of a subroutine <br> program. |
| MACRO | MCRO | 99 | Calls and executes the speci- <br> fied subroutine, substituting <br> the specified input and output <br> words for the input and output <br> words in the subroutine. |

## Interrupt Control Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| INTERVAL <br> TIMER | (@)STIM | 69 | Controls interval timers used <br> to perform scheduled inter- <br> rupts. |
| INTER- <br> RUPT <br> CONTROL | (@)INT | 89 | Performs interrupt control, <br> such as masking and unmask- <br> ing the interrupt bits for I/O in- <br> terrupts. |

## Peripheral Device Control Instructions

I/O Unit Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| 7-SEG- <br> MENT DE- <br> CODER | (@)SDEC | 78 | Converts the designated dig- <br> it(s) of a word into an 8-bit, <br> 7-segment display code. |
| I/O RE- <br> FRESH | (@)IORF | 97 | Refreshes the specified I/O <br> word. |

## Display Instruction

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| MESSAGE | (@)MSG | 46 | Reads up to 8 words of ASCII <br> code (16 characters) from <br> memory and displays the mes- <br> sage on the Programming <br> Console or other Peripheral <br> Device. |

High-speed Counter Control Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| MODE <br> CONTROL | (@)INI | 61 | Starts and stops counter op- <br> eration, compares and <br> changes counter PVs, and <br> stops pulse output. |
| PV READ | (@)PRV | 62 | Reads counter PVs and status <br> data. |
| COMPARE <br> TABLE <br> LOAD | (@)CTBL | 63 | Compares counter PVs and <br> generates a direct table or <br> starts operation. |

- Damage Diagnosis Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| FAILURE <br> ALARM | (@)FAL | 06 | Generates a non-fatal error <br> when executed. The Error/ <br> Alarm indicator flashes and the <br> CPU continues operating. |
| SEVERE <br> FAILURE <br> ALARM | FALS | 07 | Generates a fatal error when <br> executed. The Error/Alarm in- <br> dicator lights and the CPU <br> stops operating. |

## $■$ Special System Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| SET <br> CARRY | (@)STC | 40 | Sets Carry Flag 25504 to 1. |
| CLEAR <br> CARRY | (@)CLC | 41 | Sets Carry Flag 25504 to 0. |

## - RS-232C Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| RECEIVE | (@)RXD | 47 | Receives data via a commu- <br> nications port. |
| TRANSMIT | (@)TXD | 48 | Sends data via a communica- <br> tions port. |
| FCS CAL- <br> CULATE | (@)FCS | $\star$ | Checks for errors in data <br> transmitted by a Host Link <br> command. |
| ASCII-TO- <br> HEXADE- <br> CIMAL | (@)HEX | $\star$ | Converts ASCII data to hexa- <br> decimal data. |
| CHANGE <br> RS-232C <br> SETUP | (@)STUP | $\star$ | Sends the designated word <br> content (for 5 words) to the <br> system setting area of desig- <br> nated RS-232 port. |

## ■ Data Control Instructions

| Instruction | Mnemonic | Code | Function |
| :--- | :--- | :--- | :--- |
| SCALE <br> (-V2 mod- <br> els only) | (@)SCL | 66 | Performs a scaling conversion <br> on the calculated value. |
| PID CON- <br> TROL (-V2 <br> models <br> only) | PID | $\star$ | Performs PID control based on <br> the specified parameters. |
| AREA <br> RANGE <br> COMPARE <br> (See note.) | ZCP | $\star$ | Compares a value to a speci- <br> fied range. |
| 2's COM- <br> PLEMENT <br> (See note.) | (@)NEG | $\star$ | Converts 4-digit hexadecimal <br> data to its 2's complement. |

Note: These instructions can only be used with SRM1-C01/C02 models and with CX-Programmer versions 2.0 or later.

## Dimensions

## SRM1-C01/C02-V2



With Programming Console connector attached.

Note: The SRM1-C02-V2 is shown in the diagrams above. There is no RS-232C port on the SRM1-C01-V2.

## Peripheral Devices



## Standard Models

## Masters

| Model |  |  | Specifications | Standard |
| :--- | :--- | :--- | :--- | :--- |
| CompoBus/S Master | SRM1-C01-V2 | Without RS-232C port | U, C, CE |  |
|  |  |  |  |  |
|  | SRM1-C02-V2 | With RS-232C port |  |  |

## - Slaves

## Remote Terminals

| Model |  | Specifications |
| :--- | :--- | :--- |
| SRT2-ID04 | 4 transistor inputs, multiple power supply, NPN | U, C, CE |
| SRT2-ID04-1 | 4 transistor inputs, multiple power supply, PNP |  |
| SRT2-ID08 | 8 transistor inputs, multiple power supply, NPN |  |
| SRT2-ID08-1 | 8 transistor inputs, multiple power supply, PNP |  |
| SRT2-ID16 | 16 transistor inputs, multiple power supply, NPN |  |
| SRT2-ID16-1 | 16 transistor inputs, multiple power supply, PNP |  |
| SRT2-ID16T | 16 transistor inputs, multipoint common terminal, multiple power supply, NPN |  |
| SRT2-ID16T-1 | 16 transistor inputs, multipoint common terminal, multiple power supply, PNP |  |
| SRT2-OD04 | 4 transistor outputs, multiple power supply, NPN |  |
| SRT2-OD04-1 | 4 transistor outputs, multiple power supply, PNP |  |
| SRT2-OD08 | 8 transistor outputs, multiple power supply, NPN |  |
| SRT2-OD08-1 | 8 transistor outputs, multiple power supply, PNP |  |
| SRT2-OD16 | 16 transistor outputs, multiple power supply, NPN |  |
| SRT2-OD16-1 | 16 transistor outputs, multiple power supply, PNP |  |
| SRT2-OD16T | 4 transistor outputs, multiple power supply, NPN |  |
| SRT2-OD16T-1 | 16 transistor outputs, multiple power supply, PNP |  |
| SRT2-ROC08 | 8 relay outputs, local power supply |  |
| SRT2-ROC16 | 16 relay outputs, local power supply |  |
| SRT2-ROF08 | 8 power MOSFET relay outputs, local power supply |  |
| SRT2-ROF16 | 16 power MOSFET relay outputs, local power supply |  |
| SRT2-MD16T | 8 transistor inputs/8 transistor outputs, multipoint common terminal, multiple power |  |
| supply, NPN |  |  |
| SRT2-MD16T-1 | 8 transistor inputs/8 transistor outputs, multiple power supply, PNP |  |

[^0]
## Standard Models

## Connector Terminals

| Model |  | Specifications |
| :--- | :--- | :--- |
| SRT2-ID32ML | 32 inputs | CE |
| SRT2-ID32ML-1 | 32 inputs, PNP |  |
| SRT2-OD32ML | 32 outputs |  |
| SRT2-OD32ML-1 | 32 outputs, PNP |  |
| SRT2-MD32ML | 32 inputs/outputs |  |
| SRT2-MD32ML-1 | 32 inputs/outputs | U, C, CE |
| SRT2-VID08S | 8 transistor inputs, sensor cable connector, multiple power supply, NPN |  |
| SRT2-VID08S-1 | 8 transistor inputs, sensor cable connector, multiple power supply, PNP |  |
| SRT2-VID16ML | 16 transistor inputs, MIL connector, multiple power supply, NPN |  |
| SRT2-VID16ML-1 | 16 transistor inputs, MIL connector, multiple power supply, PNP |  |
| SRT2-VOD08S | 8 transistor outputs, sensor cable connector, multiple power supply, NPN |  |
| SRT2-VOD08S-1 | 8 transistor outputs, sensor cable connector, multiple power supply, PNP |  |
| SRT2-VOD16ML | 16 transistor outputs, MIL connector, multiple power supply, NPN |  |
| SRT2-VOD16ML-1 | 16 transistor outputs, MIL connector, multiple power supply, PNP |  |

## Sensor Amplifier Terminals

| Model | Specifications | Standard |
| :---: | :---: | :---: |
| SRT1-TID04S | 4 inputs (1 word $\times 4$ ), network power supply | CE |
| SRT1-TKD04S | 4 inputs (4 words $\times 1$ ), network power supply |  |
| SRT1-XID04S | 4 inputs (1 word x 4), Expansion Sensor Amplifier Terminal |  |
| SRT1-XKD04S | 4 inputs (4 words $\times 1$ ), Expansion Sensor Amplifier Terminal |  |

- Connector Units for photoelectric sensors

| Model |  | Specifications |
| :--- | :--- | :--- |
| E3X-NT16 | General-purpose, teaching, 1 channel | U, C, CE |
| E3X-NT26 | General-purpose, teaching, multi-functional, 1 channel |  |
| E3X-NM16 | General-purpose, teaching, multi-functional, 4 channels |  |
| E3X-NH16 | General-purpose, bar-display, teaching, long-distance, high-precision, 1 channel |  |
| E3X-DA16 | Digital, 1 channel |  |

- Connector Units for proximity sensors

| Model |  | Specifications |
| :--- | :--- | :--- |
| E2CY-T16 | Used for aluminum detection | U, C |
| E2C-T16 | Miniature specifications |  |

## - Terminal Block Unit

| Model |  | Specifications | Standard |
| :--- | :--- | :--- | :--- |
| E39-JID01 | 1 input | --- |  |

- U: UL, cUL: Canada UL, C: CSA, N: NK, L: LLOYD, CE: EC Directives

See OMRON sales representatives for conditions under which UL, cUL, CSA, NK, LLOYD, and CE standards were met.
Note: For details regarding CompoBus/S, refer to the CompoBus/S Catalog. (Catalog number: Q103-E1- $\square$ )

## Standard Models

## Analog I/O Terminals

| Model | Specifications | Standard |
| :--- | :--- | :--- |
| SRT2-AD04 | 4 analog inputs (settable to 1, 2, 3, or 4 inputs), network power supply | U, C, CE |
| SRT2-DA02 | 2 analog outputs (settable to 1 or 2 outputs), network power supply |  |

## Sensor Terminals

| Model |  | Specifications |
| :--- | :--- | :--- |
| SRT1-ID08S | 8 inputs, network power supply | CE |
| SRT1-OD08S | 8 outputs, local power supply |  |
| SRT1-ND08S | 4 inputs, 4 outputs, network power supply |  |

## Bit Chain Terminal

| Model | Specifications | Standard |
| :--- | :--- | :--- |
| SRT1-B1T | 8 inputs/outputs (I/O set via switch), local power supply | --- |

Note: The above model does not support long-distance communications mode.
Remote I/O Module (for mounting to PCB)

| Model | Specifications | Standard |
| :--- | :--- | :--- |
| SRT1-ID16P | 16 inputs | --- |
| SRT1-OD16P | 16 outputs |  |

## CPM1A/CPM2A/CPM2C I/O Link Unit

| Model | Specifications | Standard |
| :--- | :--- | :--- |
| CPM2C-SRT21 | Used with CPM2C PLCs; 8 inputs and 8 outputs | CE |
| CPMIA-SRT21 | Used with CPM2A and CPM1A PLCs; 8 inputs and 8 outputs | U, C, CE |

## Position Drivers

| Model |  | Standard |
| :--- | :--- | :--- |
| FND-X06H-SRT | 200-VAC input, momentary maximum output current: 6.0 A | $\mathrm{U}, \mathrm{cUL}$, |
| FND-X12H-SRT | 200-VAC input, momentary maximum output current: 12 A | CE |
| FND-X25H-SRT | 200-VAC input, momentary maximum output current: 25 A |  |
| FND-X50-SRT | 200-VAC input, momentary maximum output current: 50 A |  |
| FND-X06L-SRT | 100-VAC input, momentary maximum output current: 6.0 A |  |
| FND-X12L-SRT | 100-VAC input, momentary maximum output current: 12 A |  |

- U: UL, cUL: Canada UL, C: CSA, N: NK, L: LLOYD, CE: EC Directives

See OMRON sales representatives for conditions under which UL, CUL, CSA, NK, LLOYD, and CE standards were met.
Note: For details regarding CompoBus/S, refer to the CompoBus/S Catalog. (Catalog number: Q103-E1- $\square$ )

## Standard Models

## - Connection Devices

## Communications Cables

| Model |  | Specifications |
| :--- | :--- | :--- |
| Commercially available | VCTF cable (JIS C3306), $0.75 \mathrm{~mm}^{2} \times 2$ conductors | --- |
| SCA1-4F10 | Special Flat Cable, $100 \mathrm{~m}, 0.75 \mathrm{~mm}^{2} \times 4$ conductors |  |

## Specified Communications Cables

| Model | Manufacturer | Comments | Standard |
| :--- | :--- | :--- | :--- |
| $\# 9409$ | Belden | USA manufacturer | --- |

Note: The electrical characteristics of the above cable are the same as those of the following: VCTF cable (JIS C3306), $0.75 \mathrm{~mm}^{2} \mathrm{x}$ 2 conductors. It can thus be used with the same specifications as the VCTF cable listed above.

Connectors and Terminal Blocks

| Model | Name | Comments | Standard |
| :--- | :--- | :--- | :--- |
| SCN1-TH4 | Branch Crimp Connector | Connector used to branch from the main line. Can be used <br> only on the Special Flat Cable. | --- |
| SCN1-TH4E | Extension Crimp Connector | Used to extend the Special Flat Cable. |  |
| SCN1-TH4T | Terminating Resistor Crimp <br> Connector | A connector equipped with terminating resistance. Can be <br> used only on the Special Flat Cable. |  |
| SRT1-T | Terminal-block Terminator | A terminal block equipped with terminating resistance. Can <br> be used either on the Special Flat Cable or VCTF cable. |  |

SRM1 RS-232C Port Connecting Cable

| Model |  | Name | Specifications | Standard |
| :--- | :--- | :--- | :--- | :--- |
|  | CQM1-CIF02 | Peripheral Port Conversion <br> Cable | For connecting IBM PC/AT compatible <br> computers. (Cable length: 3.3 m$)$ | $\mathrm{U}, \mathrm{C}, \mathrm{CE}$, <br> $\mathrm{N}, \mathrm{L}$ |

## Standard Models

RS-422 Adapter

| Model |  | Name | Specifications | Standard |
| :---: | :--- | :--- | :--- | :--- |
| CPM1-CIF11 | RS-422 Adapter | For level conversion between the <br> Peripheral Port and RS-422 | CE, N, L |  |

## Link Adapters

| Model |  | Name | Specifications | Standard |
| :---: | :--- | :--- | :--- | :--- |
|  | NT-ALO01 | Link Adapter | One RS-232C connector and one <br> RS-422 terminal block. <br> Power supply: 5 VDC; 150 mA | --- |

## Link Adapter for IBM PC/AT-compatible Computers

| Model |  | Name | Specifications | Standard |
| :--- | :--- | :--- | :--- | :--- |
|  | 3G2A9-AL004-E | Link Adapter | One RS-232C connector, one RS-422 <br> connector, and one fibre-optic <br> connector. <br> Power supply: 100/200 VAC | --- |

## Peripheral Devices

| Model |  | Name | Specifications | StandardU, C, CE,N |
| :---: | :---: | :---: | :---: | :---: |
|  | CQM1-PRO01-E | CQM1 Programming Console | With cable (2 m) |  |
|  | C200H-PRO27-E | C200H Programming Console | Hand-held, with backlight; requires the C200H-CN222 or C200H-CN422, see below. |  |
|  | C200H-CN222 | C200H-PRO27-E Connecting Cable | Cable length: 2 m | N |
|  | C200H-CN422 |  | Cable length: 4 m | --- |
|  | C200H-ATT01 | Mounting Bracket | For panel mounting. |  |
| W $\begin{aligned} & \square \\ & \square\end{aligned}$ | C500-ZL3AT1-E | SYSMAC Support Software | 3.5", 2HD for IBM PC/AT compatible |  |

## Programming Device

| Model | Name | Function |
| :---: | :--- | :--- |
| WS02-CXPC1-EV2 | CX-Programmer (Windows 95/98/NT) <br> (Compatible with versions 2.0 or later.) | CD-ROM (English) |

U: UL, cUL: Canada UL, C: CSA, N: NK, L: LLOYD, CE: EC Directives
See OMRON sales representatives for conditions under which UL, cUL, CSA, NK, LLOYD, and CE standards were met.

## - Information on EC Directives

Individual OMRON products that comply with EC Directives conform to the common emission standards of EMC Directives. However, the emission characteristics of these products installed on customers' equipment may vary depending on the configuration, wir-

## Standard Models

ing, layout, and other conditions of the control panel used. For this reason, customers are requested to check whether the emission characteristics of the entire machine or equipment comply with the EMC Directives.

## Connections to a Wider Range of Slaves Ensured by Upgraded Models

|  |  |  | Master | Conventional models | New | odels |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | C200HW-SRM21 CQM1-SRM21 SRM1-C01 SRM1-C02 SRM1-C01-V1 SRM1-C02-V1 3G8B3-SRM00 3G8B3-SRM01 C200PC-ISA02-SRM C200PC-ISA12-SRM | $\begin{array}{r} \text { C200HW-s } \\ \text { CQM1-S } \\ \text { SRM1- } \\ \text { SRM1- } \\ \text { TP1000 } \\ \text { C200C-IS } \\ \text { C200PC-I } \end{array}$ | $\begin{aligned} & \text { SRM21-V1 } \\ & \text { RM21-V1 } \\ & \text { C01-V2 } \\ & \text { C02-V2 } \\ & \text {-A-SRM } \\ & \text { A03-SRM } \\ & \text { SA13-SRM } \end{aligned}$ |
|  |  |  |  | NKE-made Uniwire | Communic | tions mode |
| Slave |  |  |  | Unit SDD-CS1 | High-speed communications mode | Long-distance communications mode |
|  |  |  | SRT1 Series FND-X $\square$-SRT | $\begin{array}{\|l} \hline \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{array}{\|l} \hline \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \hline \text { No } \\ & \text { No } \end{aligned}$ |
| Products from other companies | SMC | Solenoid valve for SI manifold use | VQ Series SX Series SY Series | $\begin{array}{\|l} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{array}{\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \hline \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  | CKD | Solenoid valve for saving wiring effort | 4TB1 and 4TB2 Series 4TB3 and 4TB4 Series 4G Series MN4SO Series | Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes | No <br> No <br> Yes <br> No |
|  | Koganei | Valve for saving wiring effort | $\begin{aligned} & \text { YS1A1, A2 } \\ & \text { YS2A1, A2 } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l} \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \text { No } \\ & \text { No } \end{aligned}$ |
| Existing prod |  |  | SRT2-AD04 SRT2-DA02 | $\begin{aligned} & \hline \text { No } \\ & \text { No } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  |  |  | SRT2-VID08S(-1) <br> SRT2-VOD08S(-1) <br> SRT2-VID16ML(-1) <br> SRT2-VOD16ML(-1) | Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes |
|  |  |  | $\begin{aligned} & \text { SRT2-ID16(-1) } \\ & \text { SRT2-OD16(-1) } \\ & \text { SRT2-ID08(-1) } \\ & \text { SRT2-OD08(-1) } \\ & \text { SRT2ROC166 } \\ & \text { SRT2-ROF16 } \end{aligned}$ | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  |  |  | CPM1A-SRT21 | Yes | Yes | Yes |
|  |  |  | $\begin{aligned} & \hline \text { SRT2-ID04(-1) } \\ & \text { SRT2-OD04(-1) } \\ & \text { SRT2-ID16T ( }(-1) \\ & \text { SRT2-OD16T(-1) } \\ & \text { SRT2-MD16T (-1) } \\ & \text { SRT2-ROC08 } \\ & \text { SRT2-ROF08 } \end{aligned}$ | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes | Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes <br> Yes |
| New produc |  |  | CPM2C-SRT21 | Yes | Yes | Yes |
|  |  |  | $\begin{aligned} & \hline \text { SRT2-ID32ML (-1) } \\ & \text { SRT2-OD32ML (-1) } \\ & \text { SRT2-MD32ML (-1) } \end{aligned}$ | $\begin{array}{\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{array}{\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |

Note: 1. In high-speed communications mode, the maximum transmission distance is 100 m at a baud rate of 750 kbps . In long-distance communications mode (i.e., a newly available mode), the maximum transmission distance is 500 m at a baud rate of 93.75 kbps .
2. The SRT2-AD04 and SRT2-DA02 are available for 16-bit synchronous communications.

Notes

Notes


[^0]:    U: UL, cUL: Canada UL, C: CSA, N: NK, L: LLOYD, CE: EC Directives
    See OMRON sales representatives for conditions under which UL, cUL, CSA, NK, LLOYD, and CE standards were met.

